

The Feasibility Pump



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Primal Heuristics

- Crucial when exact methods don't work
- Crucial for the effectiveness of exact methods (=B&C) for mixed integer programming (MIP)
- Need a first feasible solution to enable:
 - bounding!
 - reduced cost fixing
 - other improving heuristics (RINS, LB, etc...)

The Problem

We want to find a feasible solution to:

$$\min \{c^T x : Ax \geq b, x_j \text{ integer for } j \in J\}$$

Notation:

- polyhedron $P = \{x : Ax \geq b\}$
- index set of integer variables J

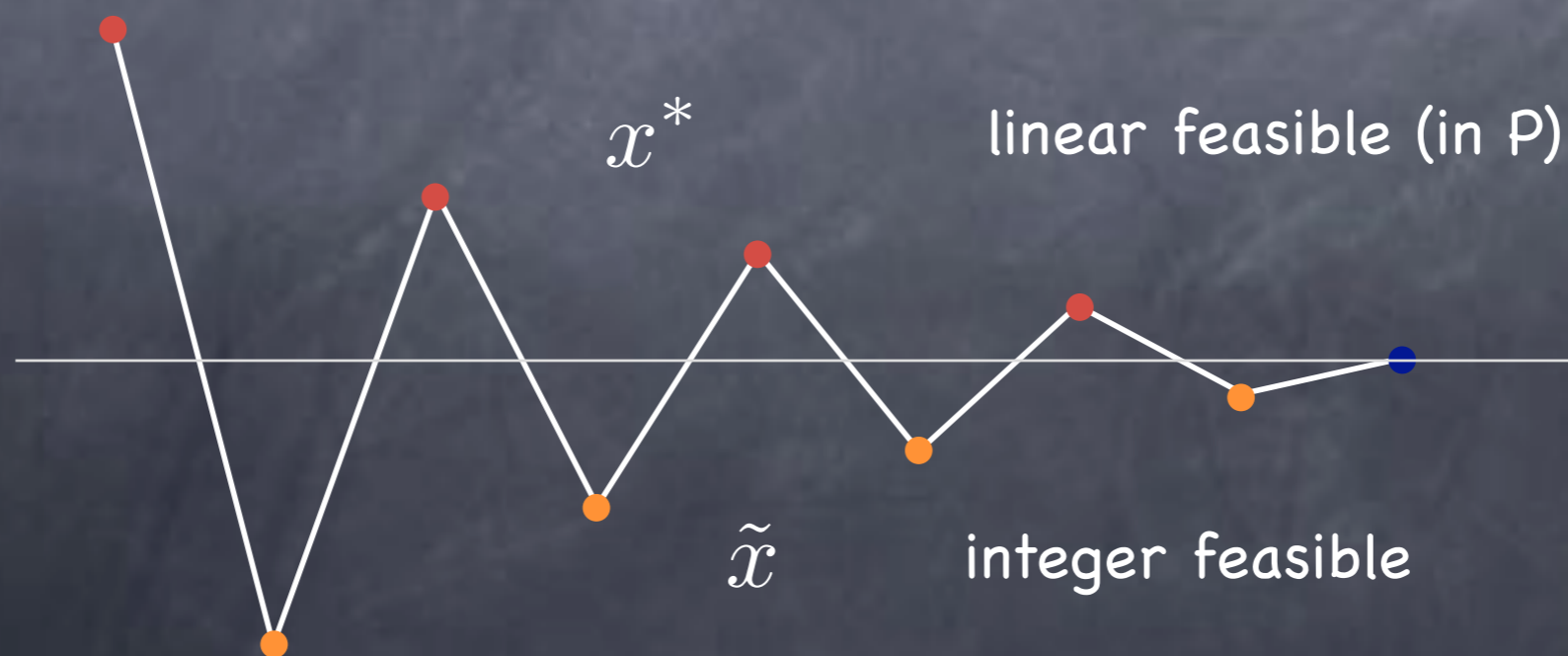
The Feasibility Pump 1.x

Fischetti, Glover, Lodi [2003]

Bertacco, Fischetti, Lodi [2005]

Achterberg, Berthold [2007]

- recent primal heuristic for MIPs
- generates two (hopefully convergent) trajectories of points x^* and \tilde{x} that satisfy feasibility in a complementary way



Basic Scheme I

How to get an integral point from a fractional one?

Plain rounding of the components in J to the nearest integer

$$\tilde{x}_j = \begin{cases} [x_j^*] & j \in J \\ x_j^* & j \notin J \end{cases}$$

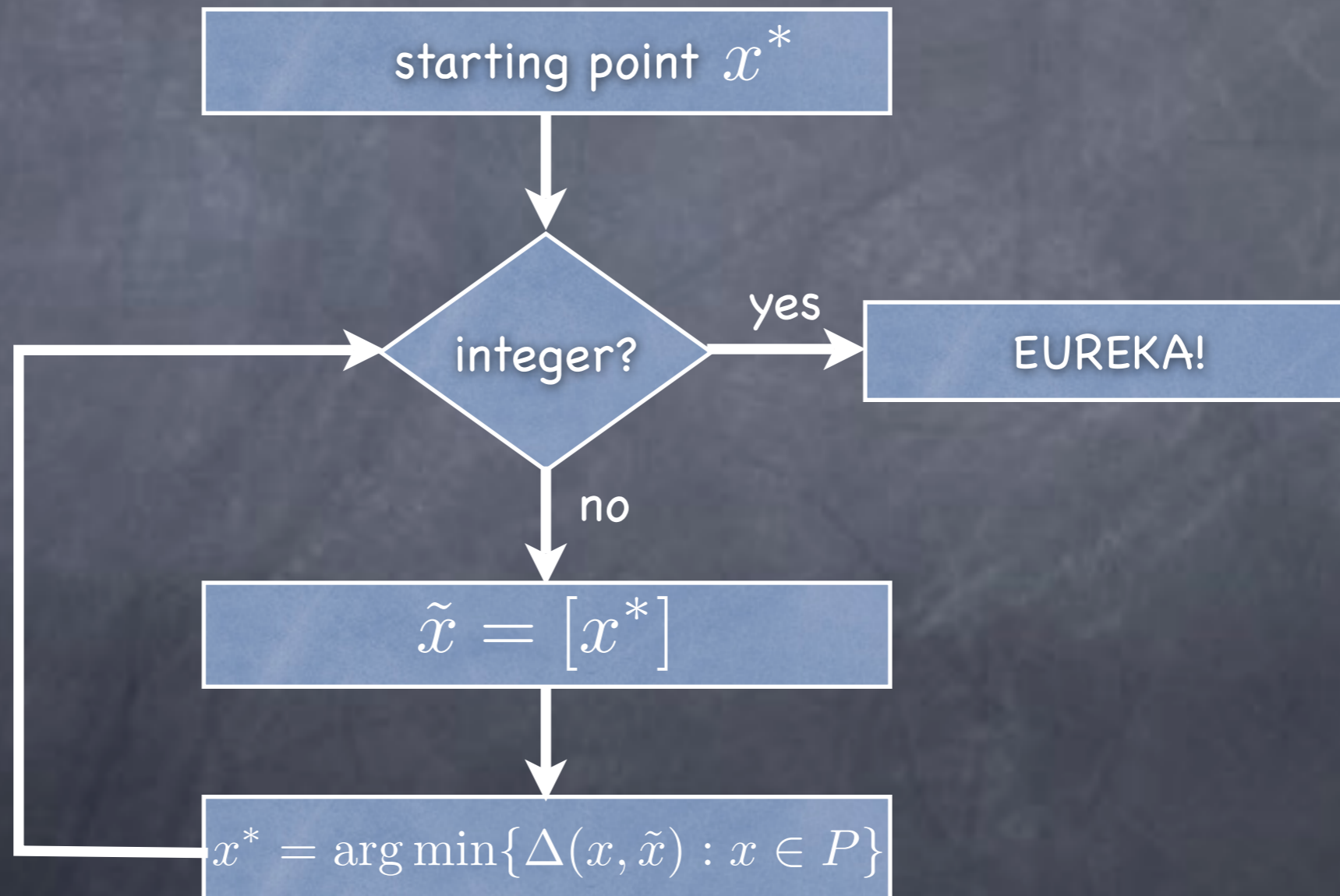
How to get an LP-feasible point from an integral one?

Find the point in P closest w.r.t the L_1 norm Δ

$$x^* = \arg \min \{ \Delta(x, \tilde{x}) : x \in P \}$$

Basic Scheme II

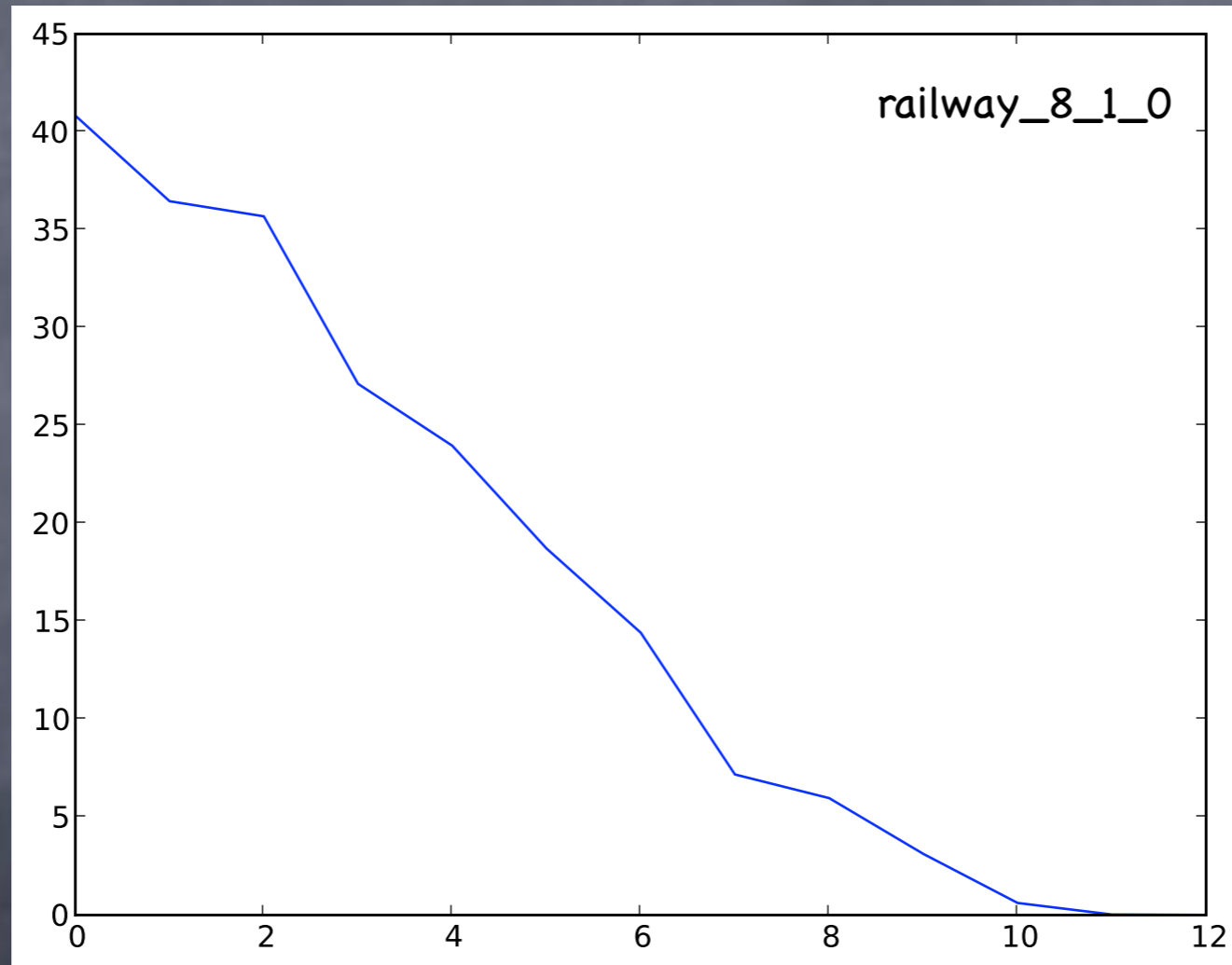
A simplified algorithm may look like this:



Cycling

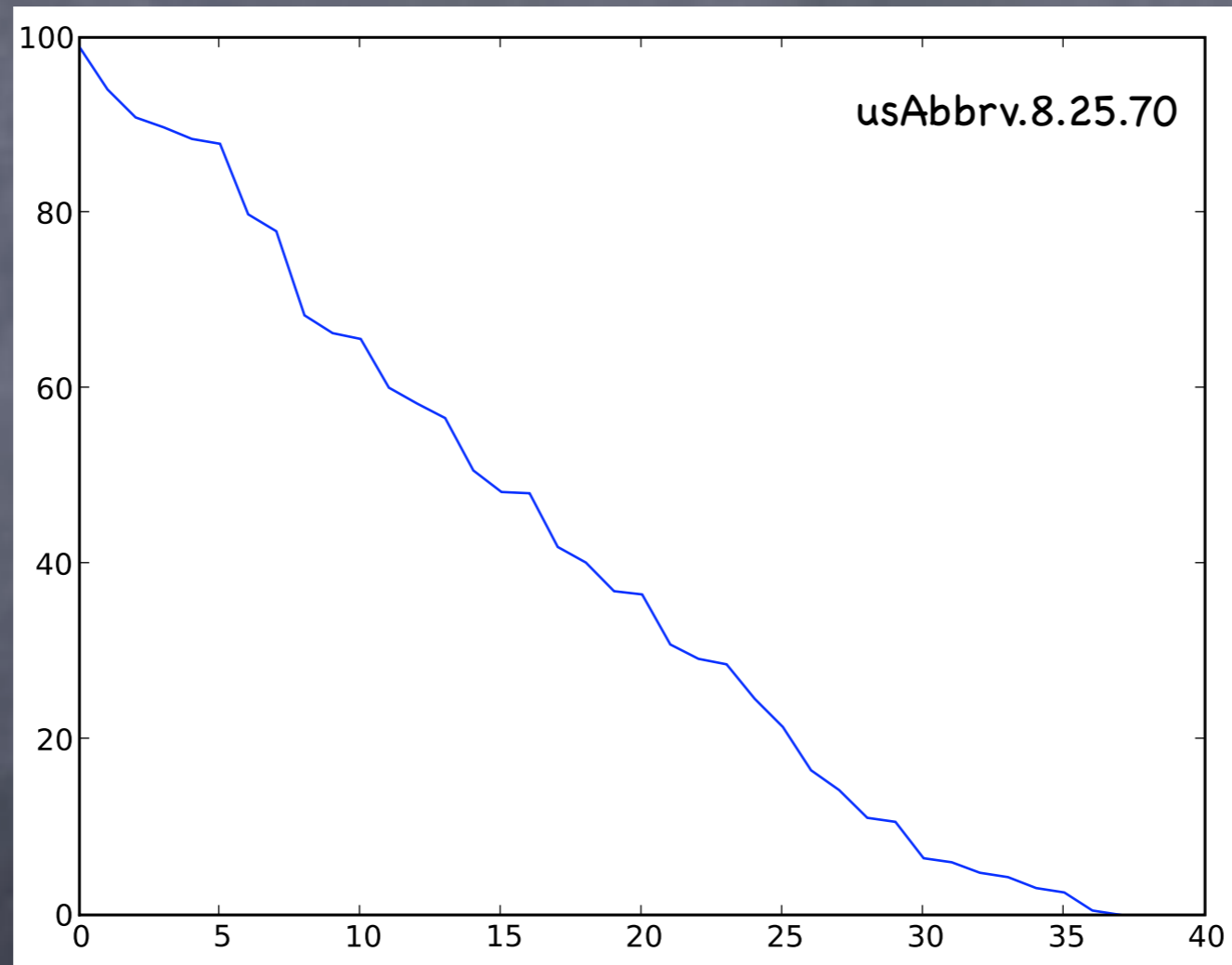
- What happens if we generate an already discovered integer solution?
- We are in a cycle!!!
- Need some anticycling mechanisms:
 - weak random perturbations
 - strong kicks (random restarts)

Real Examples



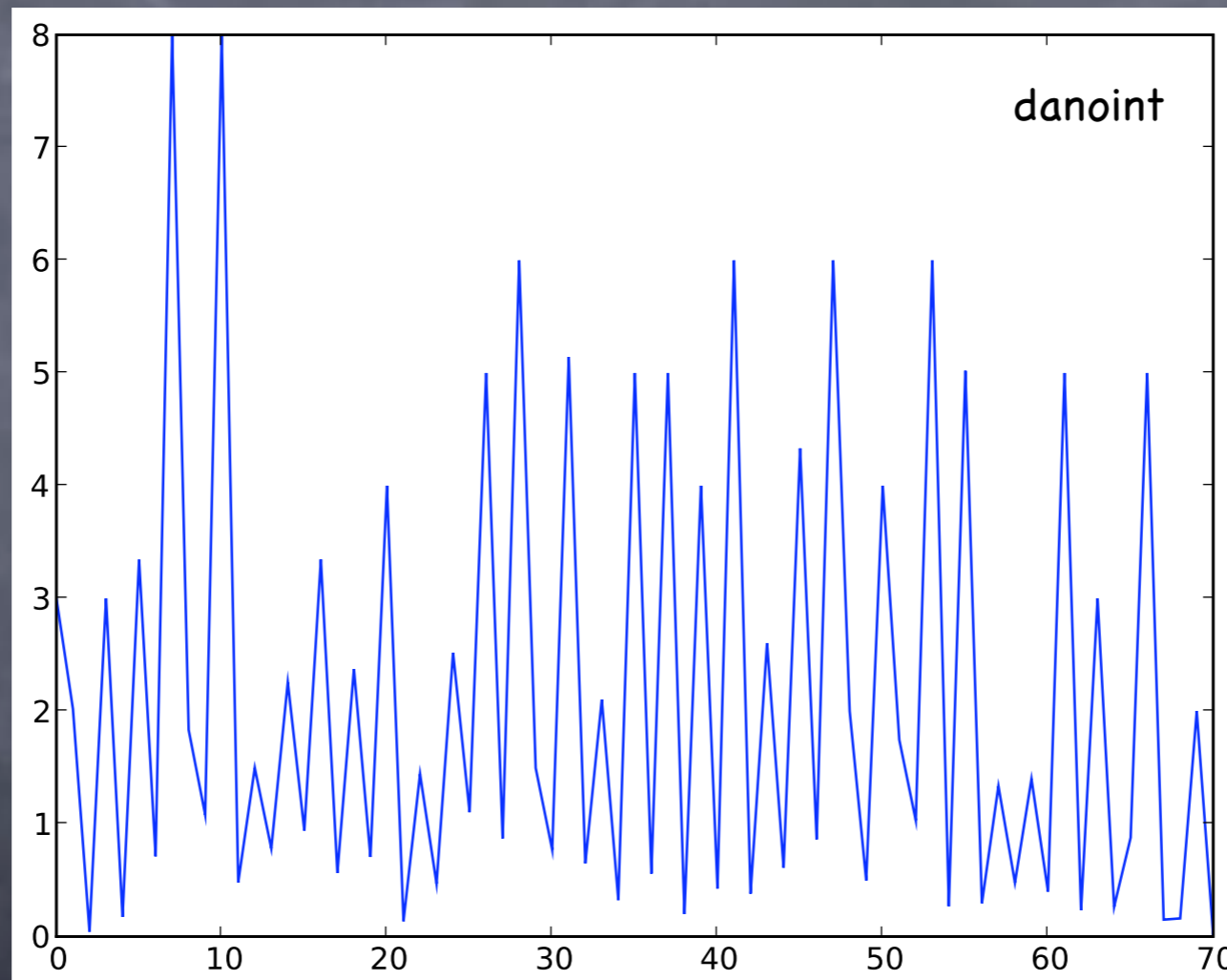
Good

Real Examples



Fair

Real Examples



Bad!

Rounding: are we serious?

Many advantages:

- + extremely simple and fast
- + $[x]$ is the nearest integer point to x
- + convergence **IN ABSENCE** of cycles

BUT:

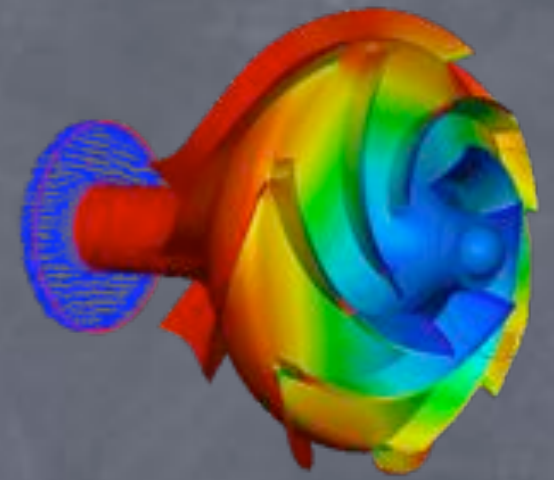
- prone to cycling (many different continuous x may map to same integral $[x]$)
- completely forgets p

FP 1.x: quick summary

- simple primal heuristics
- convergent in absence of cycles
- cycles are a big problem
- often feasible solutions are found because of frequent perturbations rather than by design
- simple rounding is quite blind and may fail on trivial instances (e.g. knapsacks, set covering)



FP 2.0: Inference!



- Rounding a variable means fixing it temporarily to a value
- Propagate the rounding of an integer variable before rounding the remaining ones
- Advantages:
 - use information from the linear constraints
 - hopefully still fast
 - akin to diving, but without solving LPs

Bound Strengthening

Savelsbergh [1994] Maros [2003] Hooker [2006] Achterberg [2007]

Given a linear constraint with positive coefficients:

$$LB \leq \sum a_j x_j \leq UB$$

and original bounds $[l_j, u_j]$ on the variables, we can compute the minimum and maximum activities:

$$L_{\min} = \sum a_j l_j \quad L_{\max} = \sum a_j u_j$$

and update variable bounds:

$$x_j \leq l_j + \frac{UB - L_{\min}}{a_j} \quad x_j \geq u_j + \frac{LB - L_{\max}}{a_j}$$

(can be rounded for integer variables and generalized to constraints with negative coefficients)

Constraint Propagation

Schulte [2000] Actherberg[2007]

- How do we organize constraint propagation?
- We use a propagator-based approach
- Basic scheme:

K : set of variables

C_i : constraint i

$C_i \supset j$: C_i involves variable j

Q : set of constraints to propagate

$Q \leftarrow \{C_i: i = 1, \dots, m\}$

while Q not empty:

$C_i \leftarrow \text{pop}(Q)$

$K \leftarrow \text{propagate}(C_i)$

$Q \leftarrow Q \cup \{C_i: C_i \supset j \text{ for some } j \text{ in } K\}$

Constraint Propagation II

- Actual implementation is more involved due to optimizations (incremental propagation and specific constraint structure exploitation)
- What's the complexity of all of this?
 - polynomial for pure binary problems
 - pseudo-polynomial for general integer
 - may not converge in a finite number of propagations for continuous variables!

NEED TO STOP PROPAGATIONS AT SOME POINT!

FP 2.0: some remarks...

- propagation can be time consuming, but is typically fast enough
- the final result depends on:
 - how we choose the next variable to round
 - the order of constraint propagators
- no dominance exists between the two versions of the FP, but FP 2.0 is strictly better on a single feasible shot

Results: testbed

- Testbed: 43 binary and 29 general integer instances from MIPLIB 2003
- Turned into feasibility problems by adding bounds on the optimal value, as a relative gap [10%, 100%, None] from the best known solution
- variables sorted by increasing fractionality before propagation
- 3 different seeds for random perturbation
- two iteration limits (IL): 20 and 250

Computational Results

Improvements w.r.t. FP 1.x

Instances	IL	Measure	Gap			Overall
			None	100%	10%	
binary	20	#found	15%	30%	19%	21%
		iterations	32%	27%	7%	19%
		time	5%	8%	3%	5%
	250	#found	7%	18%	26%	14%
		iterations	46%	44%	11%	25%
		time	31%	57%	10%	31%
general integers	20	#found	31%	100%	54%	53%
		iterations	26%	19%	6%	16%
		time	3%	9%	-5%	2%
	250	#found	14%	41%	42%	27%
		iterations	23%	23%	8%	17%
		time	4%	27%	23%	22%

Computational Results

Solution Quality

Testbed	IT	Gap	FP1 better	FP2 better	equal
binary	20	10%	4	8	31
		100%	5	19	19
		None	7	19	17
	250	10%	7	7	29
		100%	8	20	15
		None	9	21	13
general integers	20	10%	2	5	22
		100%	3	8	18
		None	8	12	9
	250	10%	2	6	21
		100%	5	11	13
		None	5	17	7
Overall	-	-	65	153	214

Conclusions

- Propagation can be very effective if embedded into the FP scheme (both for binary and general integer instances!)
 - reduced number of iterations
 - increased success rate and solution quality, in a comparable amount of time
- What's next?
 - exploit higher level modeling tools when available
 - turn attention to the LPs (maybe FP 3.0...)



Paper available (for Jack) at:
<http://www.dei.unipd.it/~fisch/papers/>