

# On Interior-Point Warmstarts for Linear and Combinatorial Optimization

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# Warmstarting

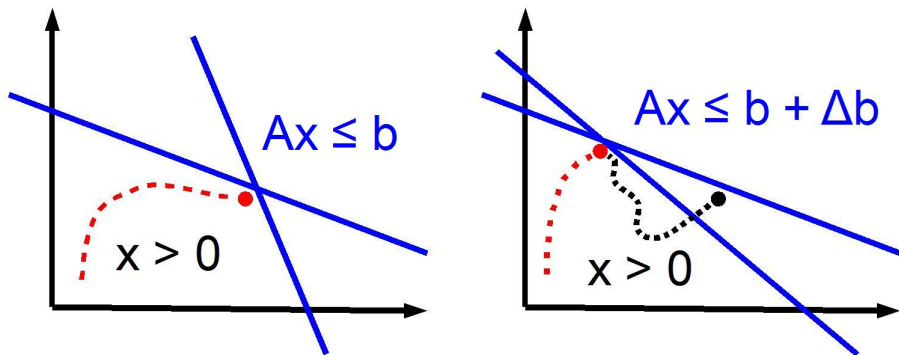
The use of information from a *solved* problem to accelerate the (re-)optimization of a *similar* problem

- 1 Same structure and size, similar data
  - changes of **right-hand side**
  - changes of **objective function**
  - changes of **real-life data** in financial and engineering applications (e.g., variation in market prices and/or product specifications)
- 2 Modified structure, more or less (of) the same data
  - **series of LP/SDP relaxations** for combinatorial optimization
  - **removal of variables and/or constraints** in branch-and-cut schemes

Results presented today are for LP, but an important motivation is to work towards **improved warmstarting** of interior-point methods (IPMs) for solving SDP relaxations of combinatorial optimization problems.

# Illustration: Inherent Problem of IPM Warmstarts

Re-optimization after right-hand side perturbation



- The active set is unchanged  $\Rightarrow$  Simplex warmstart in 1 iteration
- The interior has changed  $\Rightarrow$  effective IPM warmstart not straightforward

# Linear Programming in Primal-Dual Standard Form

$$\begin{aligned}
 \text{(LP-P)} \quad & \min c^T x \\
 & \text{s.t. } Ax = b \\
 & \quad x \geq 0
 \end{aligned}$$

$$\begin{aligned}
 \text{(LP-D)} \quad & \max b^T y \\
 & \text{s.t. } A^T y + s = c \\
 & \quad s \geq 0
 \end{aligned}$$

## First-Order (Karush-Kuhn-Tucker) Optimality Conditions

$$\begin{aligned}
 Ax = b \quad (x \geq 0) & && \text{(Primal Feasibility)} \\
 A^T y + s = c \quad (s \geq 0) & && \text{(Dual Feasibility)} \\
 x_i s_i = \mu \quad \text{for all } i & && \text{(Complementarity)}
 \end{aligned}$$

- System has a unique solution for every  $\mu > 0$  (“central path”)
- Central path converges to an optimal solution as  $\mu \rightarrow 0$
- KKT system is **nonlinear**  $\Rightarrow$  linearize & solve by **Newton's method**

**Basic Idea of Interior-Point Methods:** apply Newton's with decreasing  $\mu$

# Infeasible Primal-Dual Path-Following IPM

- 1 Initialize  $(x^0 > 0, y^0, s^0 > 0)$ , let  $\sigma \in [0, 1)$ , and set  $k = 0$ .
- 2 If  $\|Ax^k - b\| \leq \varepsilon_b$ ,  $\|A^T y^k + s^k - c\| \leq \varepsilon_c$ ,  $(x^k)^T (s^k)/n \leq \varepsilon_d$ , stop.
- 3 Set  $\mu^k = \sigma(x^k)^T (s^k)/n$  and solve for Newton direction

$$\begin{bmatrix} A & 0 & 0 \\ 0 & A^T & I \\ S^k & 0 & X^k \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \\ \Delta s \end{bmatrix} = - \begin{bmatrix} Ax^k - b \\ A^T y^k + s^k - c \\ X^k S^k e - \mu^k e \end{bmatrix}$$

- 4 Compute step length  $\alpha^k$  such that

$$x^k + \alpha^k \Delta x > 0 \text{ and } s^k + \alpha^k \Delta s > 0.$$

- 5 Take step  $(x^{k+1}, y^{k+1}, s^{k+1}) = (x^k, y^k, s^k) + \alpha^k(\Delta x, \Delta y, \Delta s)$ .
- 6 Increase  $k$  by 1 and go to Step 2.

# Warmstarting in Linear Optimization

$$\begin{array}{ll}
 \min (c^\circ + \Delta c)^T x & \max (b^\circ + \Delta b)^T y \\
 \text{s.t. } (A^\circ + \Delta A)x = b^\circ + \Delta b & \text{s.t. } (A^\circ + \Delta A)^T y + s = c^\circ + \Delta c \\
 x \geq 0 & s \geq 0
 \end{array}$$

Let  $(x^\circ \geq 0, y^\circ, s^\circ \geq 0)$  be **optimal** for the **initial problem**

$$A^\circ x^\circ = b^\circ \quad A^\circ{}^T y^\circ + s^\circ = c^\circ \quad X^\circ S^\circ e = 0$$

then  $(x^\circ, y^\circ, s^\circ)$  is **typically infeasible** for the **perturbed problem**

$$r_b^\circ = b - Ax^\circ = (b^\circ + \Delta b) - (A^\circ + \Delta A)x^\circ = \Delta b - \Delta Ax^\circ$$

$$r_c^\circ = c - A^T y^\circ - s = (c^\circ + \Delta c) - (A^\circ + \Delta A)^T y^\circ - s^\circ = \Delta c - \Delta A^T y^\circ$$

- **Good news:** Feasibility can be handled by infeasible algorithm
- **Bad news:** Initial interiority must be achieved by alternative means

# Warmstarting IPM (I): Adjustment of Initial Iterate

**Newton adjustment** (*Yildirim & Wright 2002, Gondzio & Grothey 2003*)

$$\begin{array}{rcl}
 A\Delta x & & = r_b^\circ \\
 & A^T \Delta y + & \Delta s = r_c^\circ \\
 S^\circ \Delta x & & + X^\circ \Delta s = 0
 \end{array}$$

**(Weighted) least-squares adjustments** (*Yildirim & Wright 2002*)

$$\min_{\Delta x} \|\Sigma \Delta x\| \text{ s.t. } A(x^\circ + \Delta x) = b, x^\circ + \Delta x \geq 0$$

$$\min_{\Delta y, \Delta s} \|\Lambda \Delta s\| \text{ s.t. } A^T(y^\circ + \Delta y) + (s^\circ + \Delta s) = c, s^\circ + \Delta s \geq 0$$

# Warmstarting IPM (II): Shifted-Barrier Approaches

Shifted-barrier problem (*Freund 1991*)

$$\min c^T x - \varepsilon \sum \log(x_i + \varepsilon h_i) \text{ s.t. } Ax = b, x + \varepsilon h > 0$$

Infeasible-start shifted-barrier problem (*Freund 1996*)

$$\begin{aligned} \min (c + \varepsilon(A^T y^\circ + s^\circ - c))^T x - \mu \varepsilon \sum \log(x_i) \\ \text{s.t. } Ax = b + \varepsilon(Ax^\circ - b), x > 0 \end{aligned}$$

Exact primal-dual penalty-method approach (*Benson & Shanno 2007*)

$$\min c^T x + d^T \xi$$

$$\text{s.t. } Ax = b$$

$$0 \leq x + \xi \leq u$$

$$\xi \geq 0$$

$$\max b^T y - u^T \psi$$

$$\text{s.t. } A^T y + s = c$$

$$-\psi \leq s \leq d$$

$$\psi \geq 0$$



# New: Primal-Dual Slack Approach

Key Idea: Introduce slack variables for the non-negativity constraints in both primal and dual:

$$\min c^T x$$

$$\text{s.t. } Ax = b$$

$$x - \xi = 0$$

$$\xi \geq 0$$

$$\max b^T y$$

$$\text{s.t. } A^T y + s = c$$

$$s - \psi = 0$$

$$\psi \geq 0$$

- **Good news**: Penalty parameters are no longer needed
- **Bad news**:  $x$  (and  $s$ ) are now free variables

# Theoretical (“Nice”) Complexity Results

## Iteration complexity and worst-case iteration count

- **Comparable computational cost** per iteration as standard form LP
- Detailed analysis yields **same worst-case iteration bound** as IIPM

## Initialization schemes for theoretical analysis

- **Standard form:**  $(x^0, y^0, s^0) = (\zeta e, 0, \zeta e)$  where  $\zeta \geq \|(x^*, s^*)\|_\infty$
- **Slacked form:**  $(x^0, y^0, s^0, \xi^0, \psi^0) = (x^\circ, y^\circ, s^\circ, \zeta e, \zeta e)$

## Iteration complexity of slacked-form IIPM (Engau, A., Vannelli 2008)

$$O(n) \log \left( \max \left\{ \frac{\|r_b^0\|}{\varepsilon_b}, \frac{\|r_c^0\|}{\varepsilon_c}, \frac{\|r_x^0\|}{\varepsilon_x}, \frac{\|r_s^0\|}{\varepsilon_s}, \frac{\zeta^2 n}{\varepsilon_d} \right\} \right)$$

- Easy to show that  $\max \{ \|r_x^0\|, \|r_s^0\| \} \leq \zeta^2 n$  for  $\zeta \geq \|(x^\circ, s^\circ, 1)\|_\infty$

# Practical (“Messy”) Issue: Slack Initialization

- In theory:  $(\xi^0, \psi^0) = (\zeta \mathbf{e}, \zeta \mathbf{e})$  where  $\zeta \geq \|(\mathbf{x}^*, \mathbf{s}^*)\|_\infty = \|(\xi^*, \psi^*)\|_\infty$
- In practice:  $(\xi^0, \psi^0) = (\mathbf{x}^\circ, \mathbf{s}^\circ) + (r_x^0, r_s^0)$  such that

$$\Xi^0 \Psi^0 \mathbf{e} = X^\circ S^\circ \mathbf{e} + X^\circ R_s^0 \mathbf{e} + R_x^0 S^\circ \mathbf{e} + R_x^0 R_s^0 \mathbf{e}$$

is **well-balanced** and **similar in magnitude** to  $\rho = \|(r_b^\circ, r_c^\circ, \mathbf{1})\|_\infty$ .

Also: Add **primal-dual indicator** to detect variables that are sufficiently away from zero, and do not need to be “slacked”.

# Warmstarting for LP: Perturbation Scheme

(described by *Benson & Shanno 2007* and *Gondzio & Grothey 2008*)

- **Test set:** (perturbable) **Netlib LP** problems of size  $m + n \leq 1000$
- **“LP” solver:** **SDPT3** (freely available, easy supply of initial points) with supplemental “free-variable” code by *Anjos & Burer 2008*
- **Perturbation:** **10% or 20 (random) entries of  $A, b, c$  on average**

$$\Delta c_j = \begin{cases} \epsilon \delta & \text{if } c_j^o = 0 \\ \epsilon \delta c_j^o & \text{otherwise} \end{cases} \quad \text{where } \epsilon \in [-1, 1], \delta \in \{0.1, 0.01, 0.001\}$$

(same scheme for  $b$  and  $A$  but preserving sparsity structure of  $A$ )

- **Performance measures:** perturbation levels, number of iterations

$$\text{WCR} = \text{Warm-to-Coldstart-Ratio} = \frac{\text{number of warmstart iterations}}{\text{number of coldstart iterations}}$$

# Computational Results: LP Perturbations

(Feasible) Perturbations				WCR Statistics				
$\Delta$	$\delta$	Pert	(#)	avg	stdv	min	med	max
b	0.001	15.3	46	0.23	0.14	0.06	0.17	0.63
b	0.01	14.9	42	0.28	0.14	0.11	0.25	0.65
b	0.1	15.0	40	0.39	0.18	0.15	0.36	0.82
c	0.001	17.9	62	0.24	0.13	0.08	0.20	0.64
c	0.01	18.5	59	0.33	0.17	0.11	0.28	0.90
c	0.1	18.0	54	0.44	0.22	0.13	0.40	1.13
A	0.001	19.2	60	0.32	0.20	0.13	0.25	0.87
A	0.01	19.9	58	0.41	0.25	0.14	0.37	1.74
A	0.1	19.9	58	0.58	0.27	0.21	0.56	1.75
Abc	0.001	52.8	46	0.33	0.15	0.12	0.29	0.64
Abc	0.01	51.6	42	0.46	0.17	0.13	0.45	0.83
Abc	0.1	51.5	36	0.74	0.30	0.38	0.68	1.66

# Warmstarting for Combinatorial Optimization: Max-cut

Let  $x_{ij} = \begin{cases} 1 & \text{if vertices } i \text{ and } j \text{ lie on opposite sides of the cut} \\ 0 & \text{if vertices } i \text{ and } j \text{ lie on the same side of the cut} \end{cases}$

$$\begin{array}{ll} \max & \sum_{i < j} c_{ij} x_{ij} \\ \text{subject to} & \left. \begin{array}{l} x_{ij} + x_{ik} + x_{jk} \leq 2 \\ x_{ij} - x_{ik} - x_{jk} \leq 0 \\ -x_{ij} + x_{ik} - x_{jk} \leq 0 \\ -x_{ij} - x_{ik} + x_{jk} \leq 0 \end{array} \right\} \text{for } 1 \leq i < j < k \leq n \\ & x_{ij} \in \{0, 1\} \qquad \qquad \qquad \text{for } 1 \leq i < j \leq n \end{array}$$

- Relax binary constraint to box constraint  $0 \leq x_{ij} \leq 1$
- Drop **triangle inequalities** and sequentially add constraints **as cuts**
- Solve resulting relaxations from **cold/warmstart** to compute **WCR**

# Computational Results:

## Max-cut on complete graphs

- Set of 100 randomly generated instances, up to 10 rounds of cuts

Problem size	# cuts	avg	sdev	min	med	max
30	1	0.62	0.04	0.54	0.63	0.76
30	10	0.77	0.06	0.62	0.76	0.87
30	100	1.03	0.04	0.96	1.03	1.15
60	1	0.60	0.05	0.54	0.60	0.81
60	10	0.76	0.08	0.59	0.78	0.92
60	100	0.92	0.06	0.75	0.93	1.14
100	1	0.59	0.04	0.52	0.56	0.72
100	10	0.75	0.09	0.59	0.76	0.90
100	100	0.79	0.06	0.68	0.80	0.85

# Computational Results:

## Max-cut on toroidal square grid graphs

- Set of 100 randomly generated instances, up to 10 rounds of cuts

Problem size	# cuts	avg	sdev	min	med	max
36	1	0.73	0.10	0.44	0.75	0.86
36	10	0.71	0.09	0.50	0.75	0.86
36	100	0.69	0.06	0.44	0.67	0.75
64	1	0.73	0.05	0.50	0.75	0.86
64	10	0.73	0.04	0.50	0.75	0.86
64	100	0.68	0.06	0.38	0.67	0.75
100	1	0.70	0.07	0.44	0.75	0.75
100	10	0.70	0.07	0.40	0.67	0.75
100	100	0.66	0.06	0.40	0.67	0.75



# Summary and Outlook

Take-home message: The proposed new warmstarting scheme

- is supported by theoretical and preliminary computational results
- is applicable for **data perturbations** and **new variables and/or constraints**
- consistently achieves a reduction of the iteration count by  $\geq 30\%$  in comparison with coldstart; competitive with other approaches on perturbed Netlib problems.

Where we are going from here:

- improve **benchmarking** possibilities via collection of a meaningful set of LP test problems
- carefully compare, and explore combinations, with **other warmstarting approaches**
- **extend from LP to NLP** (and particularly to SOCP and SDP)

# For Jack Edmonds (and everyone else):

- Paper is available on my webpage:  
<http://mfa.research.uwaterloo.ca>
- On the same page, there is also an online addendum with all the data files & detailed computational results.